

Solution of linear systems with square sparse matrices

Yuri Vassilevski

**Institute of Numerical Mathematics
Russian Academy of Science**

The Rome-Moscow school of Matrix Methods and Applied Linear Algebra

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Outline

- **Systems with sparse matrices**
- **Direct methods**
- **Iterative methods**
- **Concluding remarks**

Definitions

Let A be a square matrix of order n , $\det A \neq 0$:

$$A = \begin{pmatrix} a_{11} & \dots & a_{1n} \\ \vdots & \ddots & \vdots \\ a_{n1} & \dots & a_{nn} \end{pmatrix}$$

How can we solve a linear system with A and a right hand side $b \in \mathbb{R}^n$, i.e. find such $x \in \mathbb{R}^n$ that

$$Ax = b?$$

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$$A_1 = h^{-2} \begin{pmatrix} 2 & -1 & 0 & \dots \\ -1 & 2 & -1 & 0 \\ 0 & \ddots & \ddots & \ddots \\ \dots & 0 & -1 & 2 \end{pmatrix}$$

Meshes and spectral properties of matrices

Eigenvalue problem for A :

$$Aw = \lambda w$$

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$$A_1 : \quad \lambda_{\min} = 4h^{-2} \sin^2(\pi h/2) < \pi^2, \quad \lambda_{\max} = 4h^{-2} \cos^2(\pi h/2) \approx 4h^{-2}$$

$$\text{cond } A_1 = O(h^{-2})$$

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Finite differences for $-\Delta u = f$ in $\Omega = (0, 1)^2$, $u = 0$ on $\partial\Omega$:

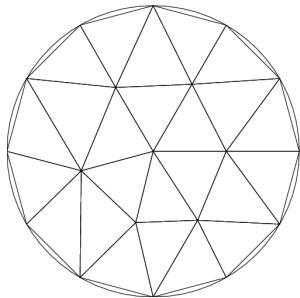
$$A_{12} = A_1 \otimes I_2 + I_1 \otimes A_2$$

$$\lambda_{\min} = 8h^{-2} \sin^2(\pi h/2) < 2\pi^2, \quad \lambda_{\max} = 8h^{-2} \cos^2(\pi h/2) \approx 8h^{-2}$$

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Finite elements for $-\Delta u = f$ in Ω , $u = 0$ on $\partial\Omega$:



quasiuniform mesh with
mesh size h

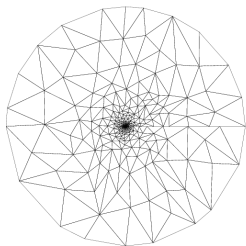
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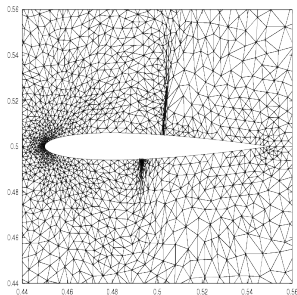
but may be

$$\lambda_{\min} = O(h_{\min}^2) \rightarrow \text{cond} A = O(h_{\min}^{-2})$$

shape regular mesh with
mesh size $[h_{\min}, h_{\max}]$

Meshes and spectral properties of matrices

Finite elements for $-\Delta u = f$ in Ω , $u = 0$ on $\partial\Omega$:



adaptive anisotropic mesh

$$\lambda_{\min} = O((\alpha h)_{\min}^2), \quad \lambda_{\max} = O(1)$$
$$\text{cond} A = O((\alpha h)_{\min}^{-2})$$

Classes of solvers

- **Strategy:**

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Sparse factorization

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$$P_1AP_2 = LU$$

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- $P_2x = z$

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- **May be inefficient for systems of PDE's**

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- Robust
- Black box
- Multiple rhs

- **Drawbacks**

- Time consuming
- Memory consuming
- Hard to parallelize
- May be inefficient for systems of PDE's

- **Implementations: UMFPACK, MUMPS, WSMP, PARDISO, SuperLU**

Sparse factorization

2D Poisson problem

$$A_{12}x = b$$

$$A_{12} = A_1 \otimes I_2 + I_1 \otimes A_2$$

$$nz_{LU} = O(n \ln n), \quad Flops = O(n^\alpha), \quad 1.5 \leq \alpha \leq 1.6$$

n_A	nz_A	<i>MB</i>	nz_{LU}	t_{factor}	t_{solve}
640000	3196800	485	$42 \cdot 10^6$	82	0.97

Sparse factorization

3D Poisson problem

$$A_{123}x = b$$

$$A_{123} = A_1 \otimes I_2 \otimes I_3 + I_1 \otimes A_2 \otimes I_3 + I_1 \otimes I_2 \otimes A_3$$

$$nz_{LU} = O(n^\alpha), \quad 1.5 \leq \alpha \leq 1.6, \quad \text{Flops} = O(n^\beta), \quad 2.2 \leq \beta \leq 2.3$$

n_A	nz_A	MB	nz_{LU}	t_{factor}	t_{solve}
125000	860000	926	$82 \cdot 10^6$	1107	1.57

Fast direct solver: Devide and conquer

Matrices from a special class

Two stages:

- Initialization
- Solution

Yuri Kuznetsov '84



rectangular non-uniform mesh

$$A_{12} = A_1 \otimes I_2 + I_1 \otimes A_2 + cI_1 \otimes I_2$$

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Systems of order 10^8 are solved at laptops within 1 min!

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Advantages:

- **Efficient**
- **Robust**
- **Parallelizable**

Abstract iterative solver

$$Ax = b$$

- **Choose an initial guess** x_0

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- $x_k = F(x_{k-1}, \dots)$, $k = 1, 2, \dots$
- ... **depend on the method**

Classical methods

Richardson's iterations:

$$x_k = x_{k-1} + \alpha(b - Ax_{k-1})$$

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In case of A_1 methods provide slow convergence, but fast frequencies are dumped quickly

$$\|e_k\| \leq (1 - ch^2)\|e_{k-1}\|, \quad e_k = x - x_k$$

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Decompose A as

$$\omega A = (D - \omega E) - (\omega F + (1 - \omega)D)$$

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In case of A_1 methods provide better convergence if ω is optimal:

$$\|e_k\| \leq (1 - ch)\|e_{k-1}\|, \quad e_k = x - x_k$$

Krylov subspace methods

- $x_m - x_0 \in \mathcal{K}_m$, $\mathcal{K}_m = \text{span}\{r_0, Ar_0, \dots, A^{m-1}r_0\}$, $r_0 = b - Ax_0$

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- **Objectives:** automatic choice of parameters and fast convergence
- **Convergence depends on spectral bounds. In case of A_1 and CG:**

$$\|e_k\|_A \leq 2(1 - ch)^k \|e_0\|_A$$

Preconditioning

$$Ax = b \Rightarrow M^{-1}Ax = M^{-1}b$$

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- **Krylov subspace methods may be preconditioned**

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- **Symmetric SOR** $M = (D - \omega E)D^{-1}(D - \omega F)$

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- Example: ILU (I.Kaporin,98), Poisson equation in $(0, 1)^2$

mesh	n_A	n_{z_A}	$n_{z_{LU}}$	t_{factor}	t_{solve}	itr_{PCG}
$1t_{2h}$	66049	460289	$1.1 \cdot 10^6$	2.2	2.5	62
$1t$	263169	1838081	$4.4 \cdot 10^6$	11.6	27.2	126
3c	229343	1605267	$3.7 \cdot 10^6$	11.8	39.9	242

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dependence on h : $[1t_{2h}, 1t]$

dependence on mesh structure: $[1t, 3c]$

$n_{zLU} \sim n$ for the same sparsity

Multigrid preconditioner

- **Assume a sequence of K hierarchical meshes be given**

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 - 3 $w_0 = A_0^{-1} u_0$

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 - 3 $w_0 = A_0^{-1} u_0$
 - 4 For $l = 1, 2, \dots, K$: $y_l = x_l + I_l w_{l-1}, w_l = y_l + R_l(u_l - A_l y_l)$,

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- Assume a sequence of K hierarchical meshes be given
- Idea: high frequency errors are damped by a smoother, low frequency errors are damped on coarser meshes
- Introduce matrix A_l and smoother (Jacobi) R_l on mesh l , interpolator P_l from mesh l to $l - 1$, prolongator I_l from mesh $l - 1$ to l .
- Evaluation of $M^{-1}v$:
 - 1 Set $u_K = v$
 - 2 For $l = K, K - 1, \dots, 1$: $x_l = R_l u_l, u_{l-1} = P_l(u_l - A_l x_l)$,
 - 3 $w_0 = A_0^{-1} u_0$
 - 4 For $l = 1, 2, \dots, K$: $y_l = x_l + I_l w_{l-1}, w_l = y_l + R_l(u_l - A_l y_l)$,
 - 5 Set $M^{-1}v = w_K$

Multigrid preconditioner

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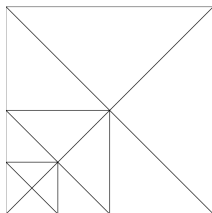
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Multigrid preconditioner

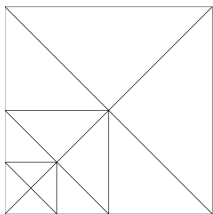
Extensions:



- **Locally refined meshes**

Multigrid preconditioner

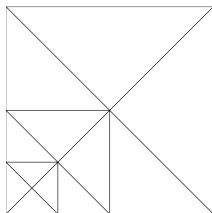
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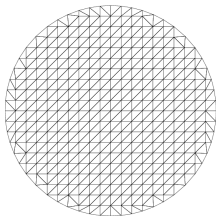
Multigrid preconditioner

Extensions:



- **Locally refined meshes**
- **Multilevel methods (BPX)**
- **Algebraic multigrids (black box)**

Fictitious domain preconditioner

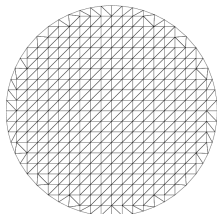


**FEM discretization of
Poisson equation
with Neumann b.c.**

Astrakhancev, Kuznetsov, Matsokin 70's

$$\begin{pmatrix} A_{11} & A_{1\Gamma} \\ A_{\Gamma 1} & A_{\Gamma}^{(1)} \end{pmatrix} \begin{pmatrix} x_1 \\ x_{\Gamma} \end{pmatrix} = \begin{pmatrix} b_1 \\ b_{\Gamma} \end{pmatrix}$$

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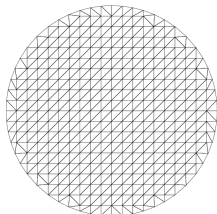
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Consider extension B

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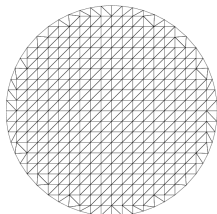
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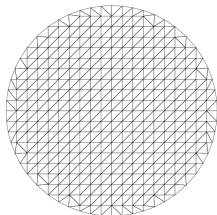
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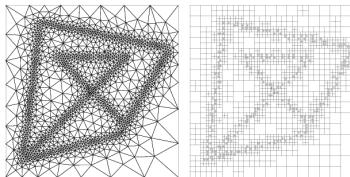
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fast convergence, parallel, partial solutions

Fictitious space preconditioner



Nepomnyaschikh '91

$$M^{-1} = R\tilde{M}^{-1}R^*$$

Domain decomposition preconditioner

- Split computational domain Ω into m nonoverlapping subdomains Ω_i

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- Fast convergence, parallel, only preconditioners, extension to large m (Mandel '93)

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- **Vast field of research**